

Altair® FluxMotor® 2025

Direct Current Permanent Magnet Machine - Inner rotor

Motor Factory - Design

General user information

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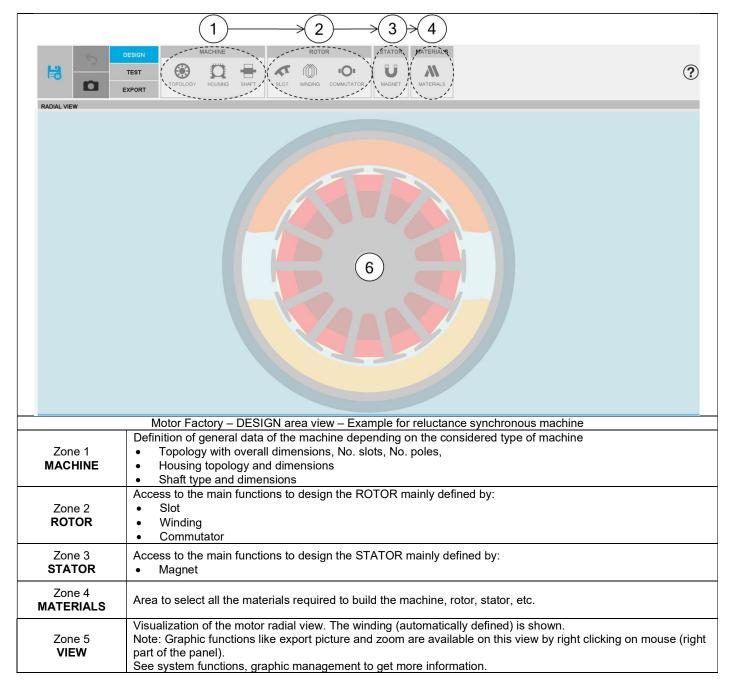
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DIRECT CURRENT PERMANENT MAGNET MACHINE

1.1 Home page view

The Motor Factory – DESIGN area is the first environment of Motor Factory. It is composed of four main zones. This is the guided line to design your machine.

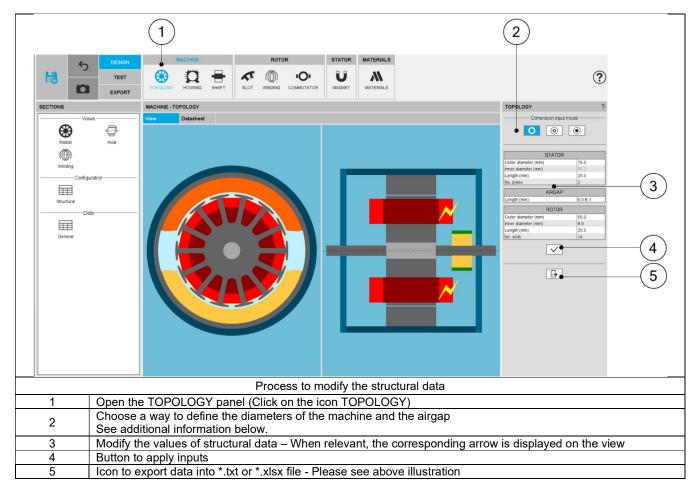




1.2 Topology

1.2.1 Overview

The first step of the design consists of defining structural data of the machine. However, at any time, it is possible to reach and modify the structural data from the Motor Factory design environment. Here is the process to modify the structural data from the general data panel.



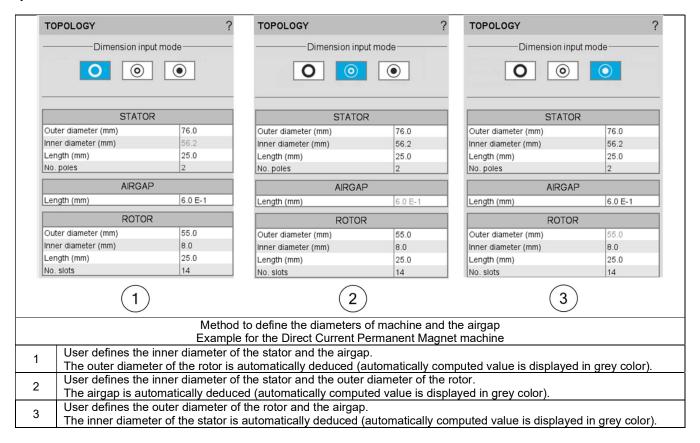
For more details concerning general functions of Motor Factory Design environment, please refer to the document MotorFactory_Introduction".



1.2.2 Inputs

1.2.2.1 Method to define the airgap

In the topology sub area, three ways are possible to define the structural data of the machine based upon the diameters and the airgap. They are illustrated below.



1.2.2.2 Structural data

Here are the user input parameters to define the structural data of the machine:

- Stator outer diameter
- Stator inner diameter
- Stator length
- Number of poles
- Airgap length
- · Rotor outer diameter
- Rotor inner diameter
- Rotor length
- Number of slots

The modification of the structural data can lead to the modification of the user input parameters in defining dimensions of parts like slots or magnets. When modifications occur, a warning is displayed.

The application ranges for structural data are defined below.



1.2.3 Advice for use

The choice of diameters is possible over the range [1, 20000] mm.

The number of slots is possible over the range [3, 2400].

The number of poles is possible over the range [2, 400].

Note: Our processes for building and computations have been qualified over the following data ranges:

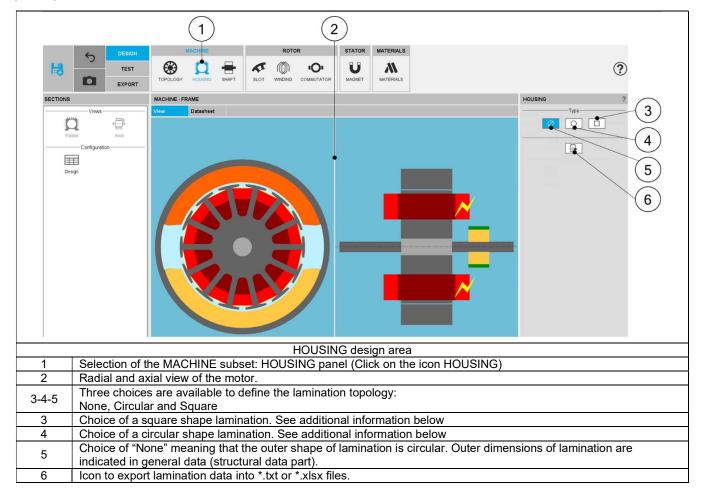
Range for diameters [1, 1000] mm. Range for number of slots [3, 90]. Range for number of poles [2, 80].

Working beyond these limits is possible but accurate results are the responsibility of the user.



1.3 Housing

1.3.1 Overview



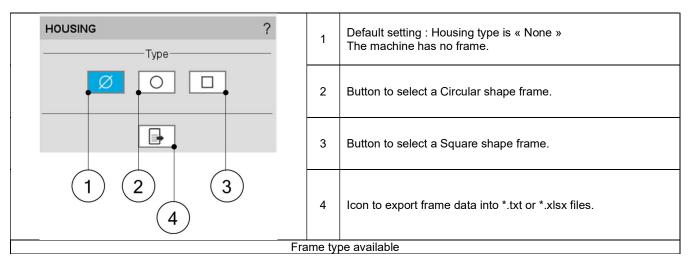


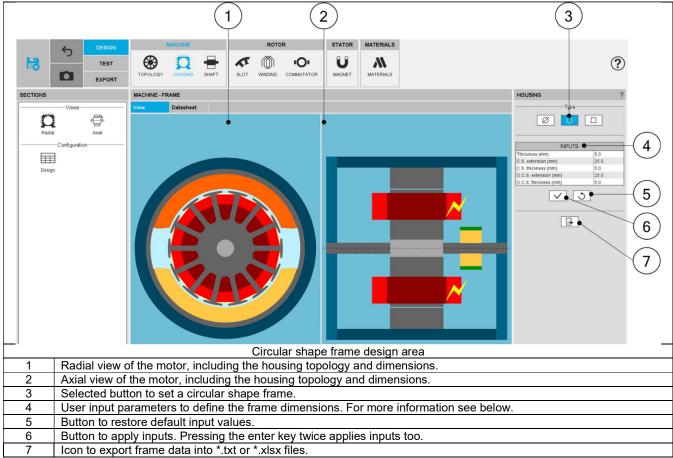
1.3.2 Housing - Frame

1.3.2.1 Type of frame

The tools available in the housing tab allow defining the frame topology. Three choices are available to define this topology: None, Circular or Square.

By default, housing type is set to "None". There is no frame.



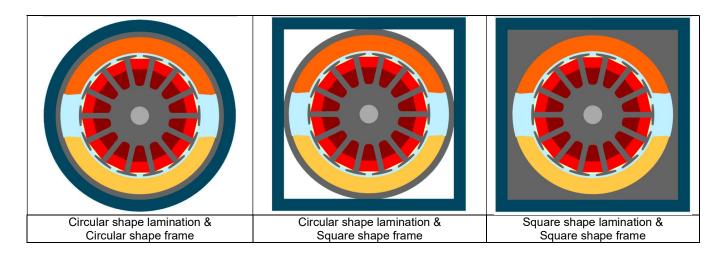




| 1 | 1 | Thickness of the frame. Allowed range of values]0, 50] mm. | |
|--|---|--|--|
| 2 | 2 | Connection side (C.S.) is identified by yellow lightning. | |
| 6 | 3 | Connection side extension. Allowed range of values [0, 20000] mm. | |
| 5 | 4 | Connection side – End-plate thickness. Allowed range of values [0, 50] mm. | |
| | 5 | Opposite connection side extension. Allowed range of values [0, 20000] mm. | |
| | 6 | Opposite connection side – End-plate thickness. Allowed range of values [0, 50] mm. | |
| User input parameters to define frame dimensions in the axial view | | | |

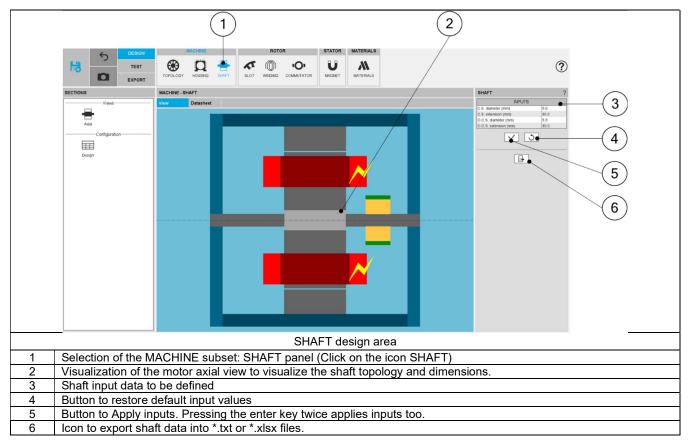
1.3.2.2 Combination between lamination outer shape and frame types

| | | Frame type | | |
|------------------------|----------|------------|--------------|--------|
| | | None | Circular | Square |
| | None | ν | ν | ν |
| Lamination outer shape | Circular | ν | ν | ν |
| outer enape | Square | ν | Not possible | ν |



1.4 Shaft

1.4.1 Overview

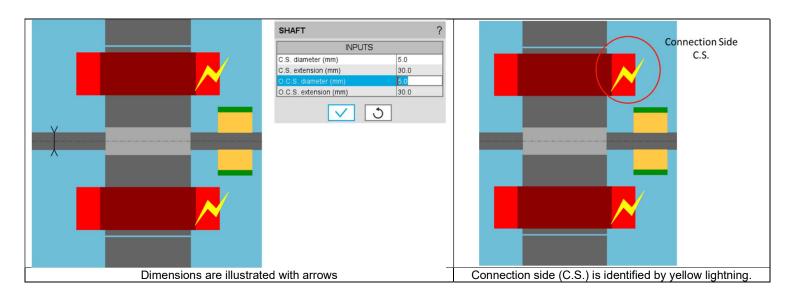


Note: Notice that for a DC machine a shaft must always be defined, since it is necessary to support the commutator.



1.4.2 Shaft type

For DC PM machine a solid shaft is imperatively selected, i.e. shaft is always represented and considered in the rotor design. It is built with a solid material or laminations



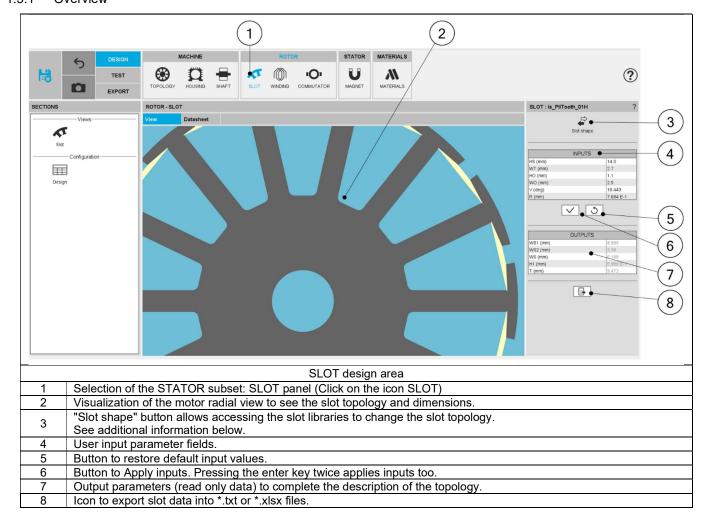
1.4.3 Shaft - Inputs

| Label | Symbol | Tooltip, note, formula |
|------------------|--------|---|
| C.S. diameter | D1 | Connection side end-shaft diameter. |
| C.S. extension | L1 | Connection side end-shaft extension. |
| O.C.S. diameter | D2 | Opposite connection side end-shaft diameter. |
| O.C.S. extension | L2 | Opposite connection side end-shaft extension. |



1.5 Slot

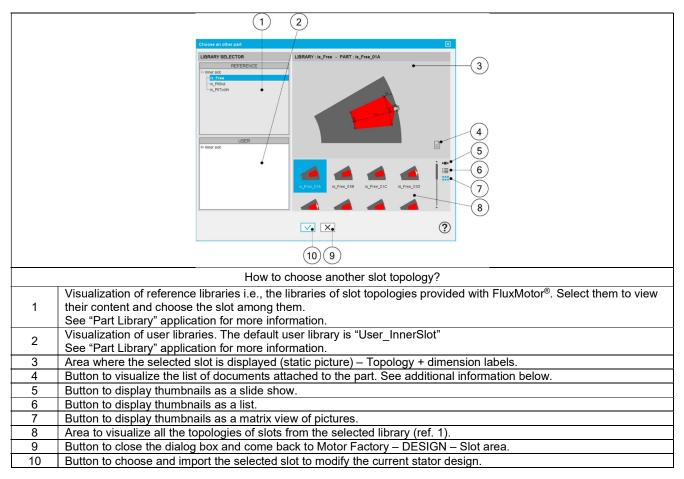
1.5.1 Overview



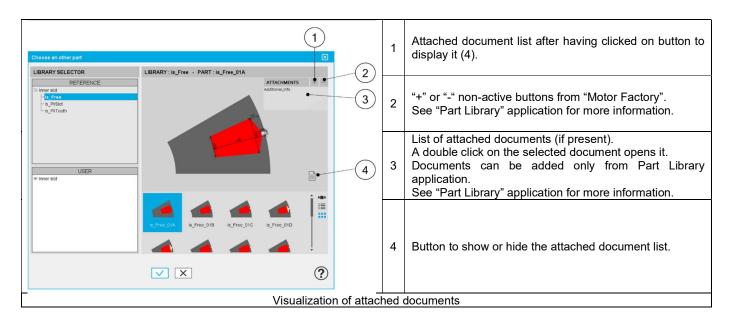
1.5.2 Slot - Design

1.5.2.1 Slot shape - Choose a slot topology

Clicking on the "Slot shape" button opens a dialog box, allowing access to the slot libraries. It allows visualizing, comparing, choosing, and importing another slot topology to modify in the current stator design.



1.5.2.2 Attached documents – Additional information





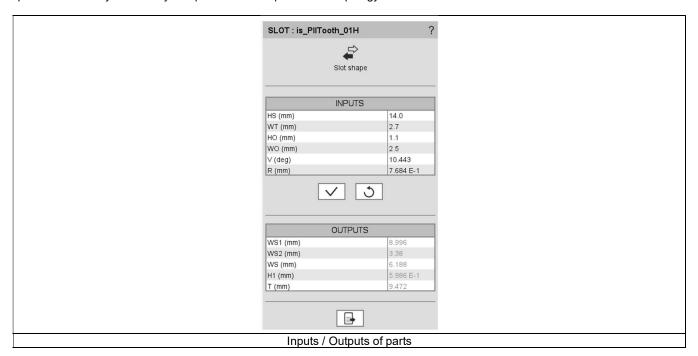
1.5.2.3 Inputs / Outputs

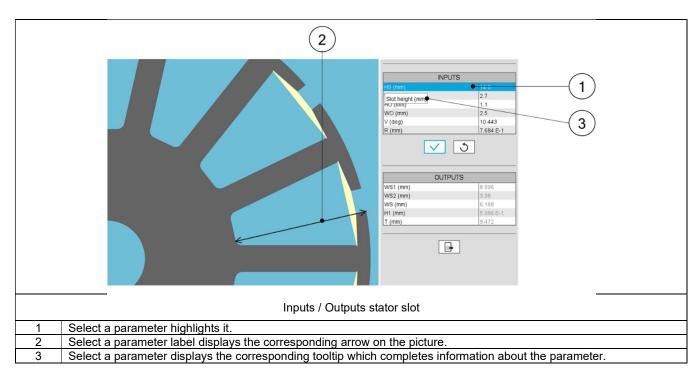
Specific inputs and outputs are considered for each slot topology.

The relevance of input parameters values can be evaluated by using "Part Factory" application.

See "Part Factory" application for more information.

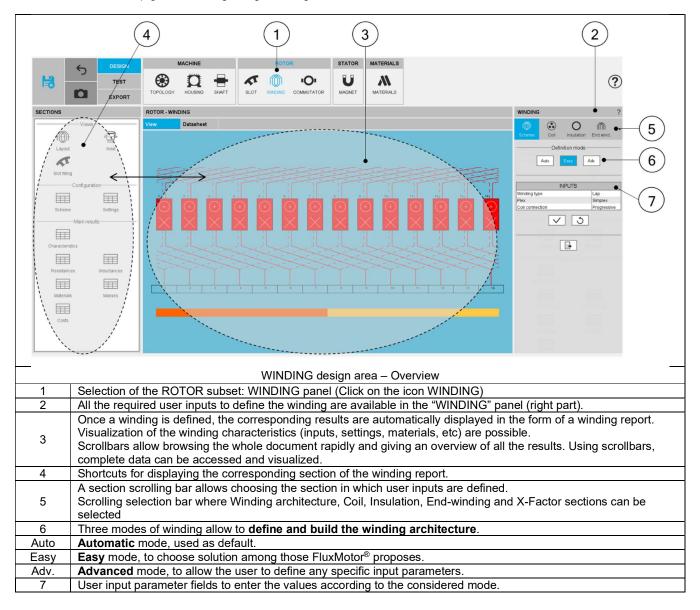
Outputs are read only data. They complete the description of the topology.





1.6 Winding

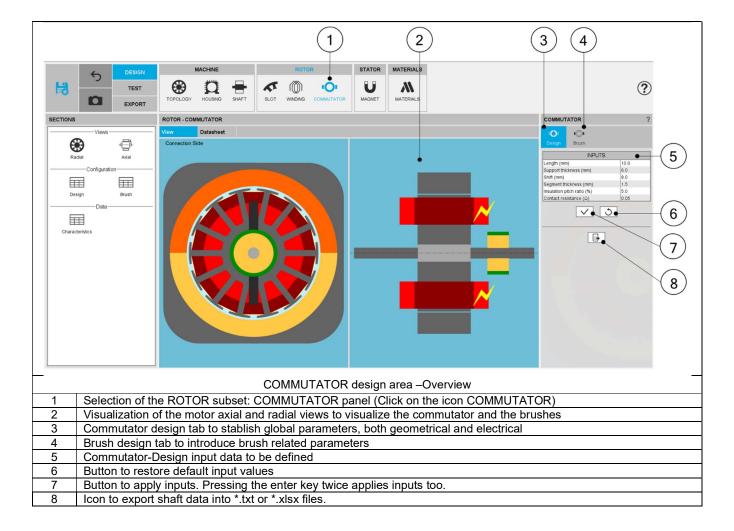
Please refer to the user help guide "Windings" to get more general user information.





1.7 Commutator

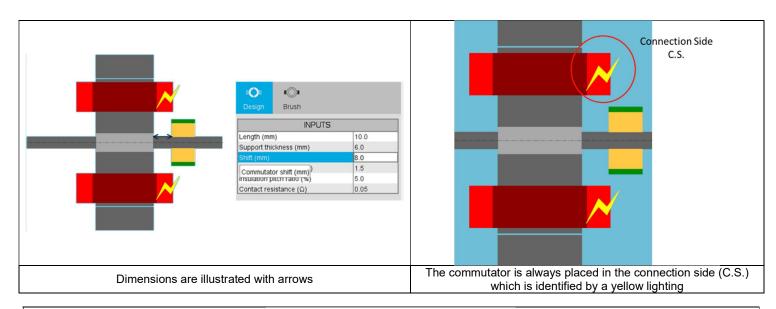
1.7.1 Overview

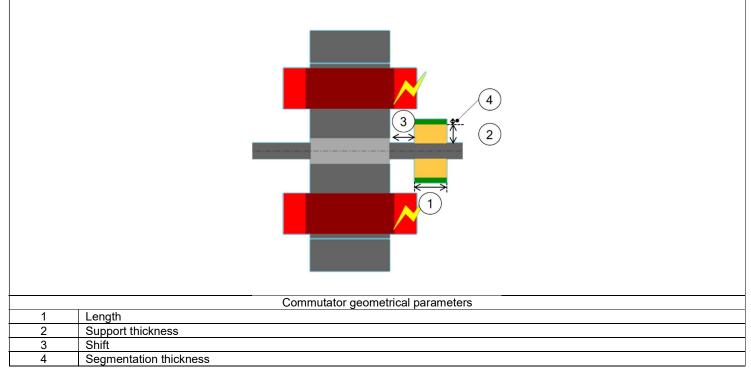


1.7.2 Commutator – Design input parameters

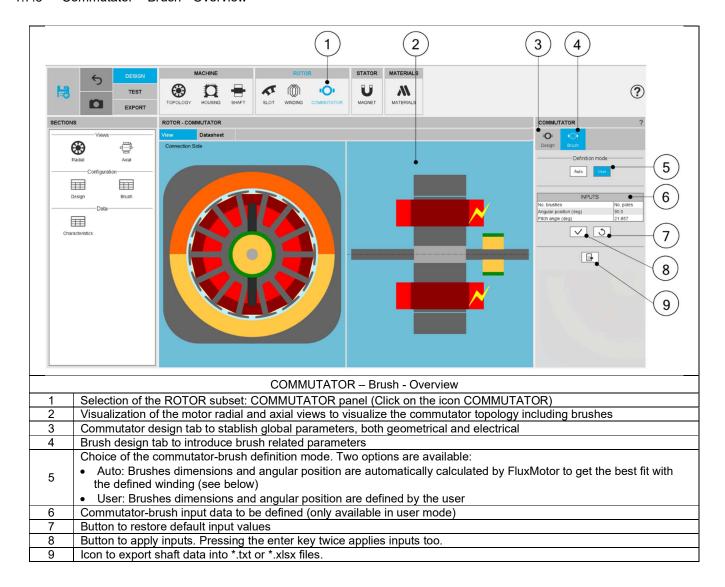
Note: By definition, the commutator is always placed in the connection side (C.S.) which is identified by a yellow lighting.

| Label | Tooltip, note |
|------------------------|---|
| Length | Commutator axial length. |
| Support thickness | Thickness of the not conducting material that is supporting the commutator segments. Since it has cylindrical form it corresponds to its radius. |
| Shift | Commutator shift |
| Segmentation thickness | Thickness of the conductive commutator segments. |
| Insulation pitch ratio | Angular ratio of the insulation between commutator segments |
| Contact resistance | Contact resistance between the brushes and the commutator segments |





1.7.3 Commutator - Brush - Overview





1.7.4 Commutator – Brush input parameters

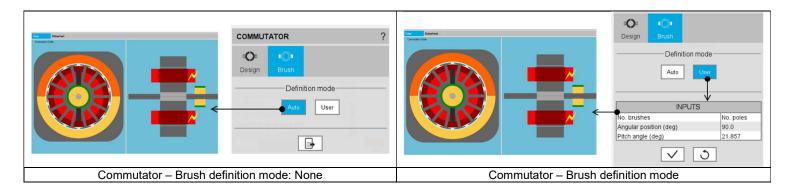
Two definition modes can be chosen for brushes

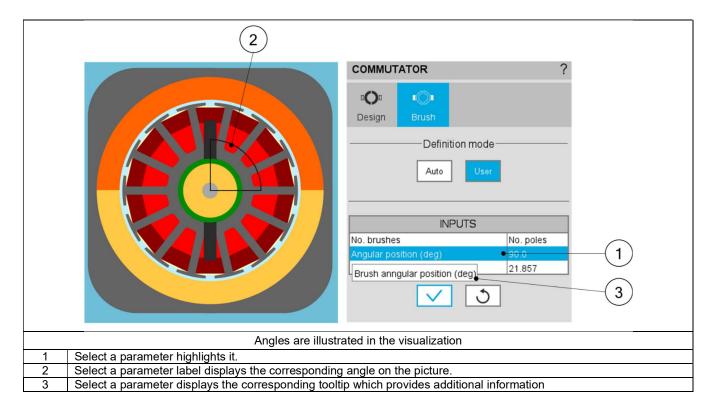
 Auto: Brushes dimensions and angular position are automatically calculated by FluxMotor to get the best fit with the defined winding. No input needed.

• User: Brushes dimensions and angular position are defined by the user.

The table below contains the brush input and their default values for "auto" mode.

| Label | Tooltip, note | Default value (auto mode) |
|---------------------|--|---|
| No of brushes | Number of brushes. Only unblocked for wave winding | Number of poles |
| Angular position | Angular position of the reference brush (polarity +) | Center of a north pole (for lap winding) |
| 7 trigular position | | Center of a south pole (for wave winding) |
| Pitch angle | Pitch angle of a brush | 0.85 times the segment commutator pitch for simplex |
| Filch angle | | winding (1.85 for duplex and 2.85 for triplex) |

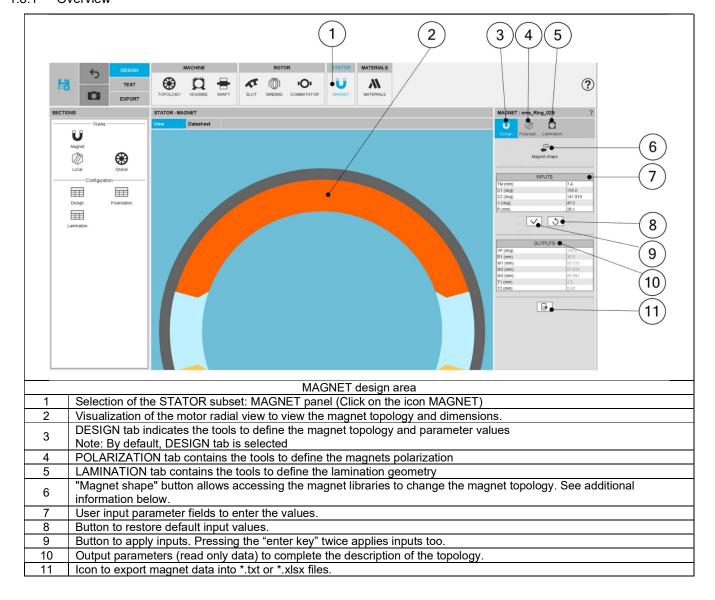






1.8 Magnet

1.8.1 Overview

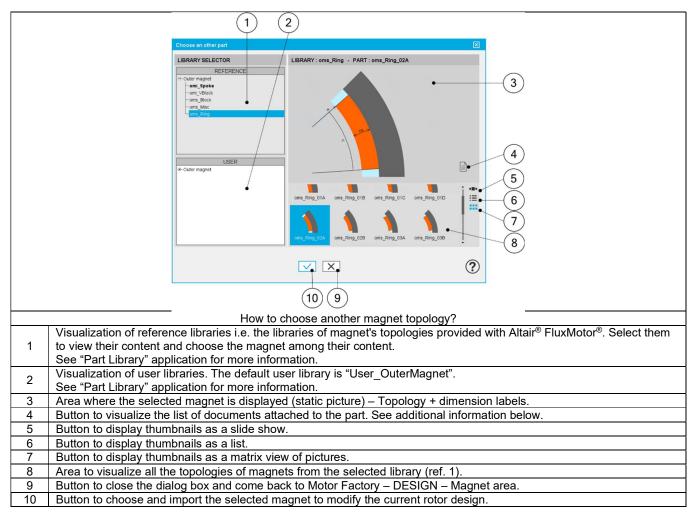




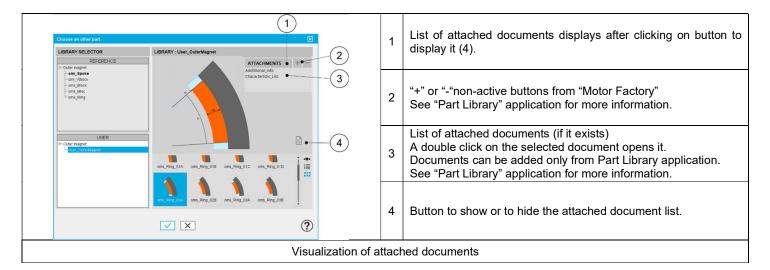
1.8.2 Magnet - Design

1.8.2.1 Choose a magnet topology

Clicking on the "Magnet shape" button opens a dialog box, allowing to access the magnet libraries. It allows visualizing, comparing, choosing, and importing another magnet topology to modify in the current rotor design.



1.8.2.2 Attached documents – Additional information





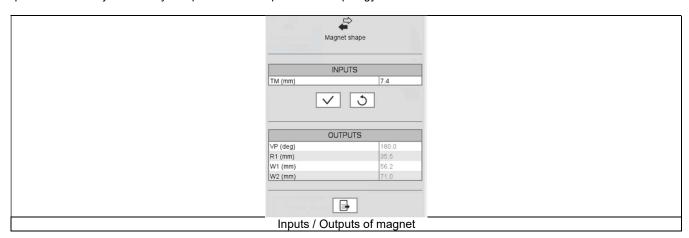
1.8.2.3 Inputs / Outputs

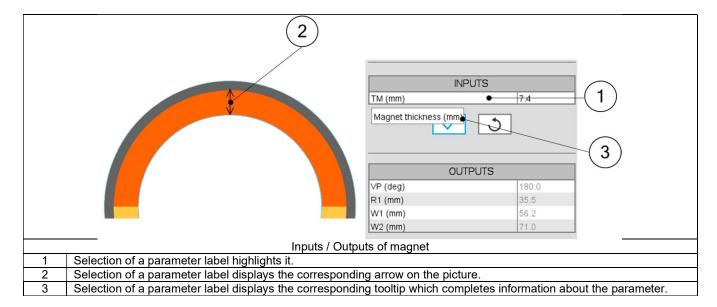
Specific inputs and outputs are considered for magnet topology.

The relevance of input parameter values can be evaluated by using "Part Factory" application.

See "Part Factory" application for more information.

Outputs are read only data. They complete the description of the topology.

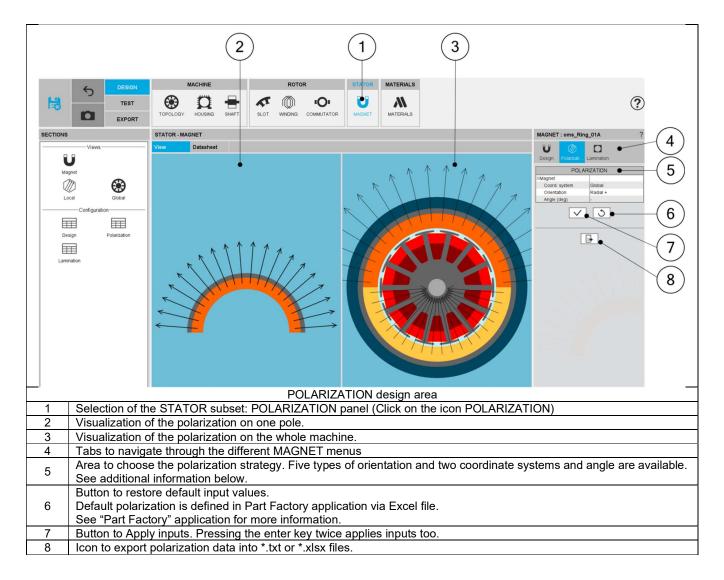






1.8.3 Magnet - Polarization

1.8.3.1 Overview



1.8.3.2 Choice of polarization

Polarization coordinate system

Two coordinate systems are available:

A "Global" polarization coordinate system: The origin is positioned at the rotor center.

A "Local" polarization coordinate system which is specific to each considered magnet topology.

Note: The reference axis (X-axis for Cartesian coordinate system) has a red color.

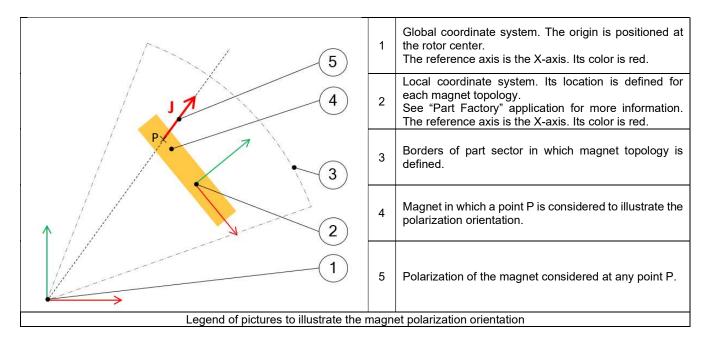
Polarization orientation

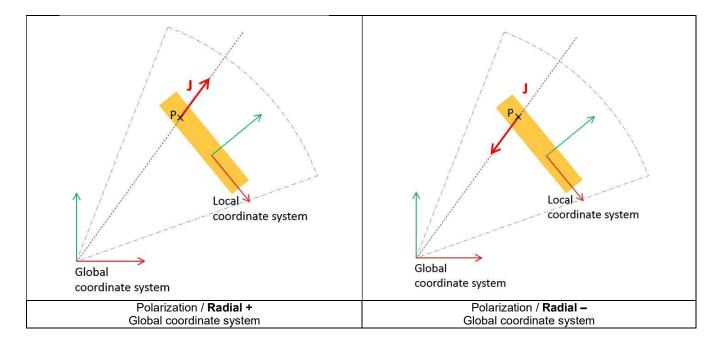
Five strategies of polarization are proposed:

- Direction
- Radial +, Radial –
- Orthoradial +, Orthoradial –

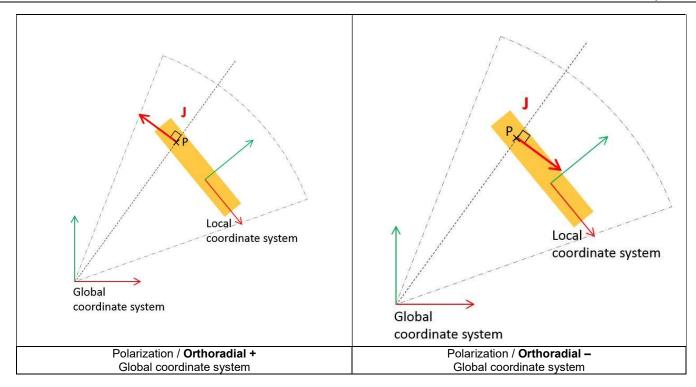


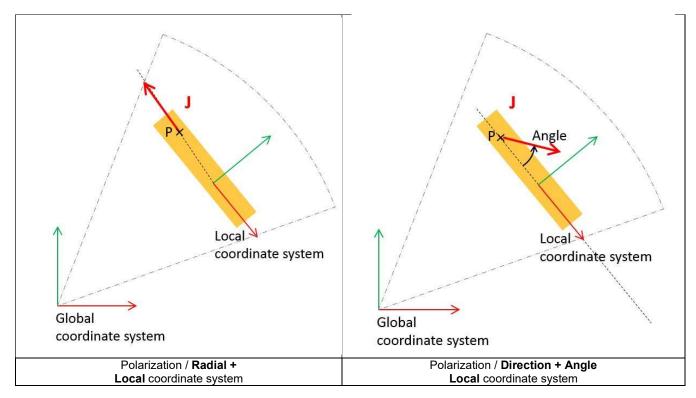
1) Polarization orientation illustrations











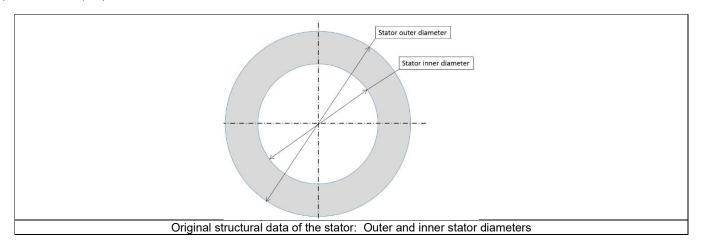
1.8.4 Magnet – Lamination

1.8.4.1 Overview

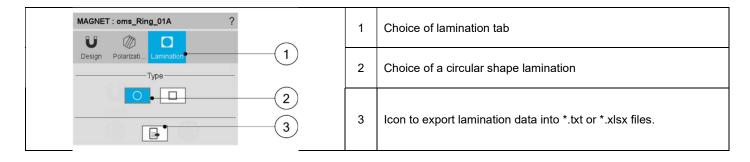
The tools available in the lamination tab allow in defining the outer shape of the lamination.

Three choices are available to define the lamination topology: Circular or Square.

By default, the outer shape of the lamination is defined by considering the outer diameter of the stator (defined in structural data). In that case outer shape of lamination is circular without extensions. Outer dimensions of lamination are indicated in general data (structural data part). See illustration below.



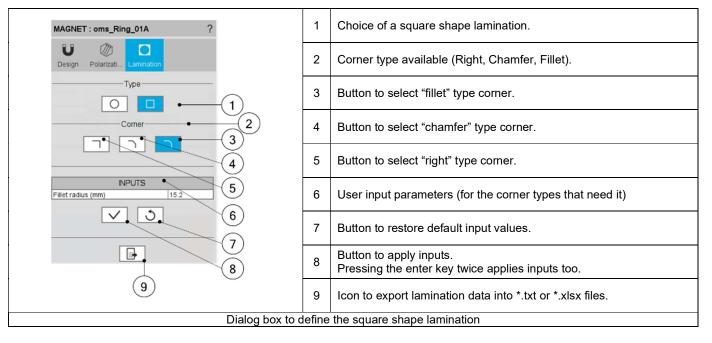
1.8.4.2 Circular shape lamination



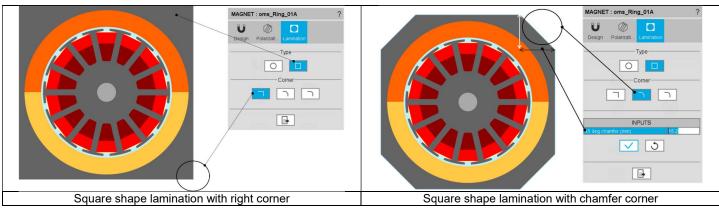


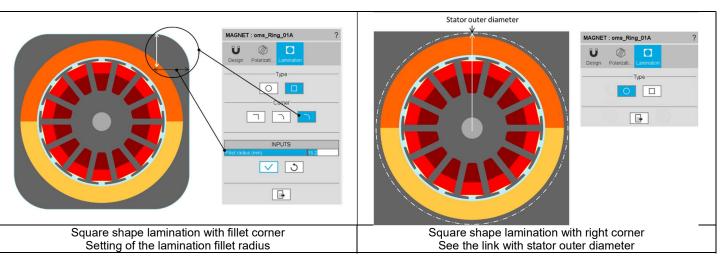
1.8.4.3 Square shape lamination

1) Main inputs



2) Description of the different kinds of square shape lamination available

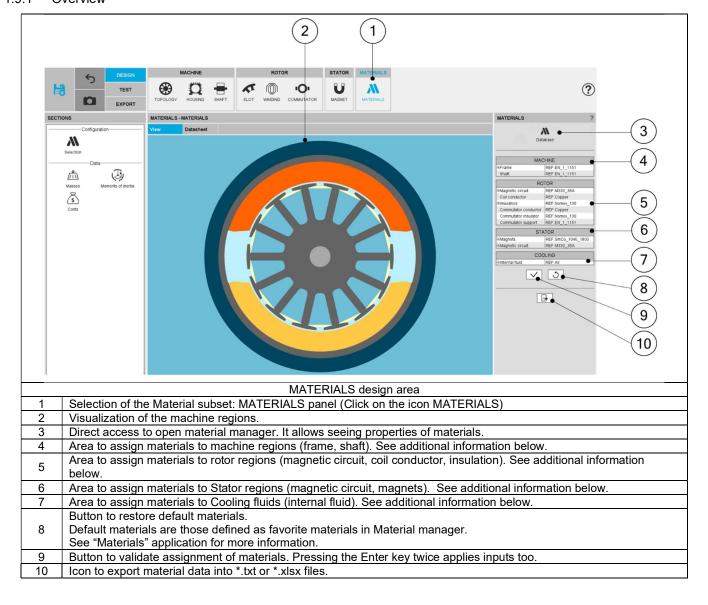






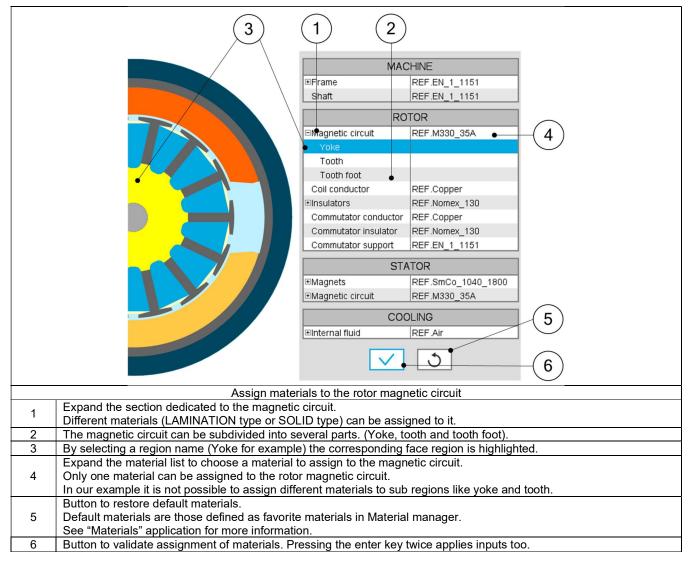
1.9 Materials

1.9.1 Overview





1.9.2 How to assign materials – Example for rotor lamination



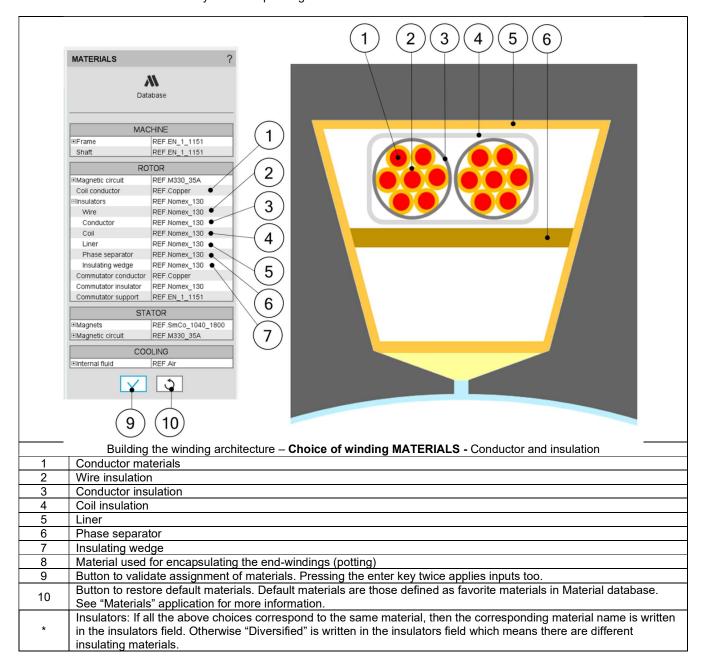
For more information about the rules leading to the building of parts like slots, please refer to Part Factory application.



1.9.3 Materials for the winding

All the materials are selected in the material database.

Conductor materials are selected in the "Electrical Conductor" type material family. Insulator materials are selected in the "Electrical Insulator" type material family. Thicknesses of insulations are defined inside the winding settings panel – COIL tab. Insulation materials are considered only if a corresponding thickness is defined.



1.9.4 Material datasheet

